

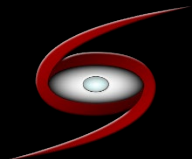
Quantifying ECLSS Robustness for Deep Space Exploration

ICES Paper 2019-239

Christine Escobar & Adam Escobar, Space Lab Technologies, LLC

Dr. James Nabity, University of Colorado at Boulder

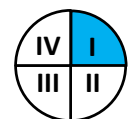




OVERVIEW

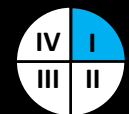


- I. The Need for Robust ECLSS Design**
- II. Robust Design Methodology for ECLSS**
- III. Quantifying ECLSS Robustness**
- IV. Improving ECLSS Robustness**

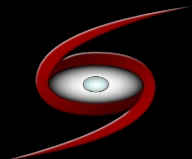




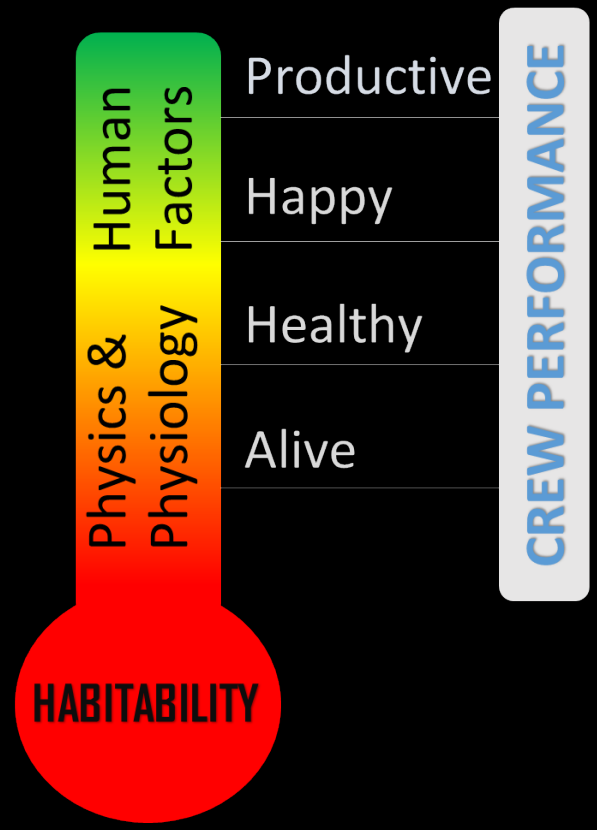
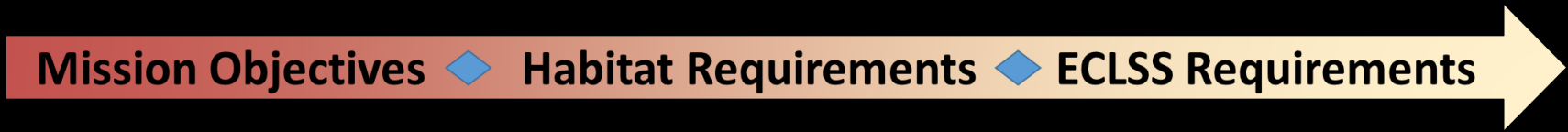
NEED FOR ROBUST ECLSS DESIGN



International Conference on Environmental
Systems, Boston, MA 2019



ECLSS REQUIREMENTS



Physics & Physiology

- Regulate the Atmosphere
- Provide Potable Water
- Remove Waste Hazards
- Food

Human Factors

- Safety Infrastructure
- Health Countermeasures
- Crew Accommodations

Design Drivers

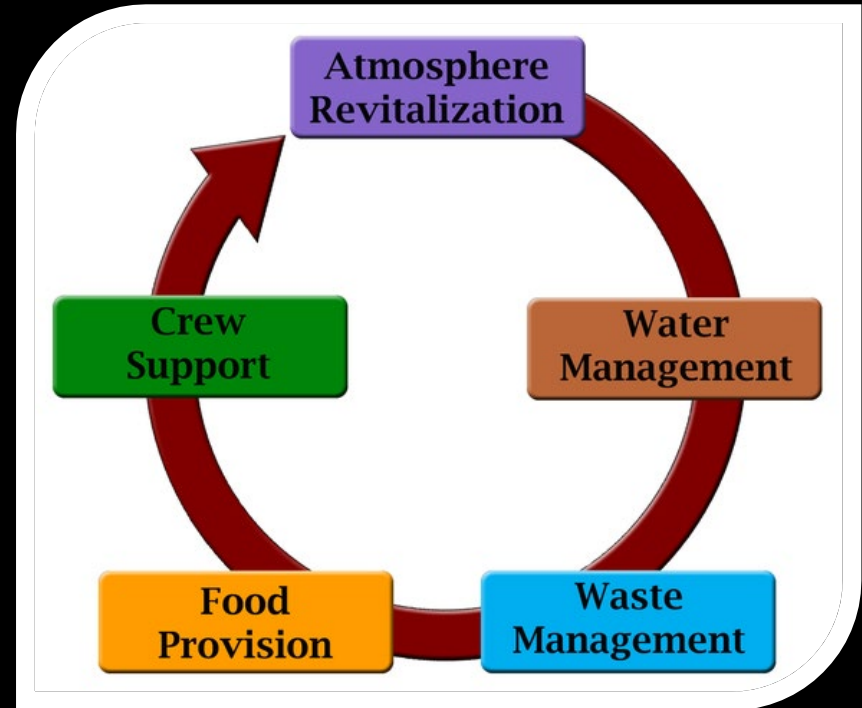
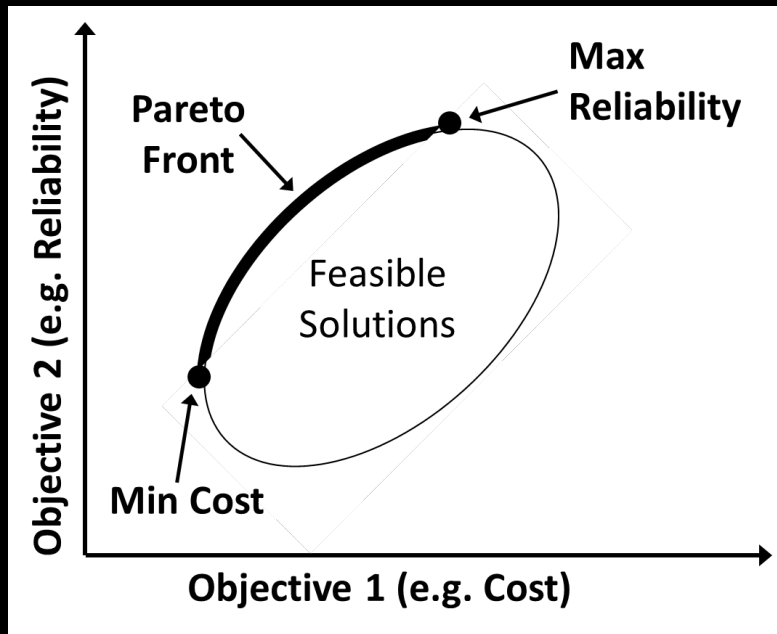
- Human metabolic inputs & outputs
- Space environment
- Mission characteristics



ECLSS DESIGN OPTIMIZATION

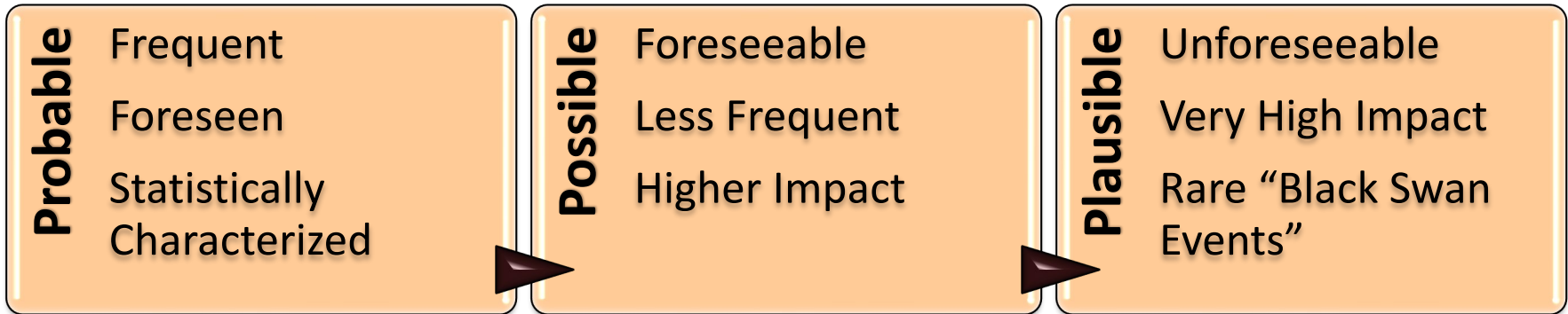


Pareto Front for Multi-Objective Optimization



Optimization finds the best possible design solution amongst all available solutions

SOURCES OF UNCERTAINTY



Aleatory (Irreducible Randomness) → Epistemic (Reducible Lack of Knowledge)

Complexity + Increased Life → Increased Variability

Sources of Uncertainty:

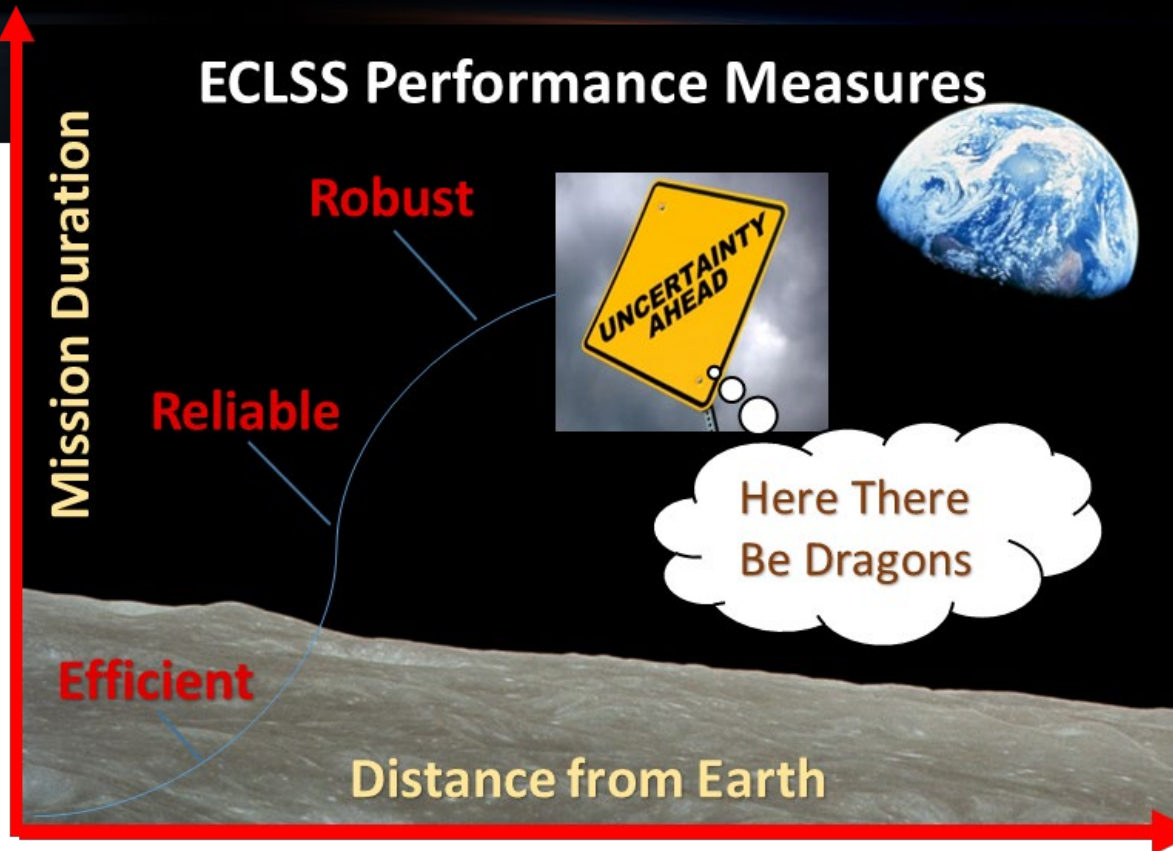
- Component Performance
- System Dynamics
- Metric Uncertainty
- Operating Environment
- Mission Characteristics



COST OF UNCERTAINTY



- **Failure Costs:**
LoC, LoV, LoM
- **Cost of Prevention:**
Redundancy, margin, etc.
- **Unanticipated system behavior in un-tested environments**
- **Increased Complexity:**
Lower reliability & higher maintenance costs



“COST OF QUALITY”

Cost of uncertainty rises with mission duration & distance, increasing importance of **ROBUSTNESS** relative to other optimization criteria





A PROPOSED ROBUST DESIGN METHODOLOGY FOR ECLSS

DEFINING ECLSS ROBUSTNESS



“Capable of performing without failure under a wide range of conditions”

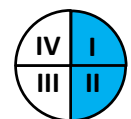
Merriam-Webster

“Often [spacecraft] systems are forced to operate under conditions which deviate significantly from ideal design conditions. A degree of how well a system performs with **no appreciable degradation** in performance **under such conditions** is measured by its **robustness**.” *Miller et al. (2008)*

ECLSS robustness is its ability to **maintain habitable** conditions for crew survival and productivity over the mission lifetime under a **wide range of conditions**.

Escobar et al., 2017

- **Ordinary usage (Reliability)**
- **Temporary disturbances or disruptions (Robustness or Resilience)**
- **Long term system or mission changes (Resilience or Survivability)**



ROBUST SYSTEM CHARACTERISTICS



RELIABLE



RESILIENT

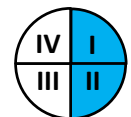
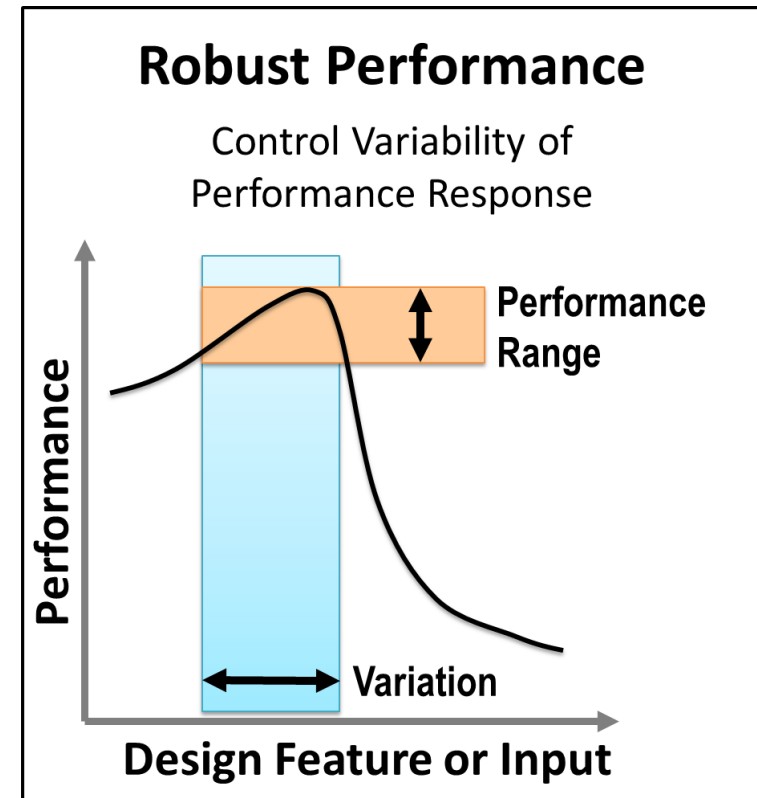
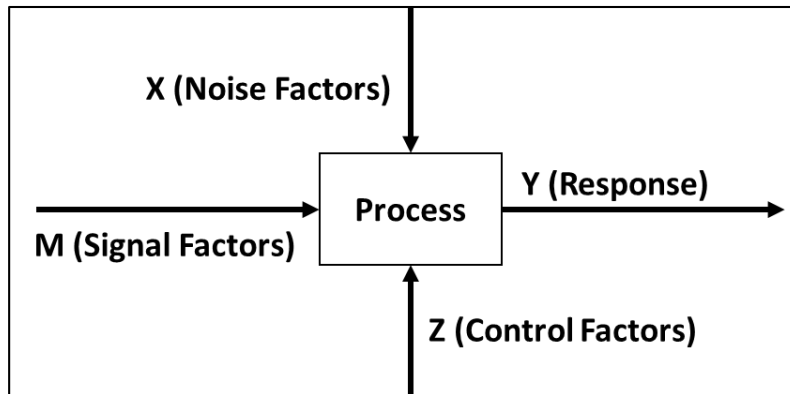
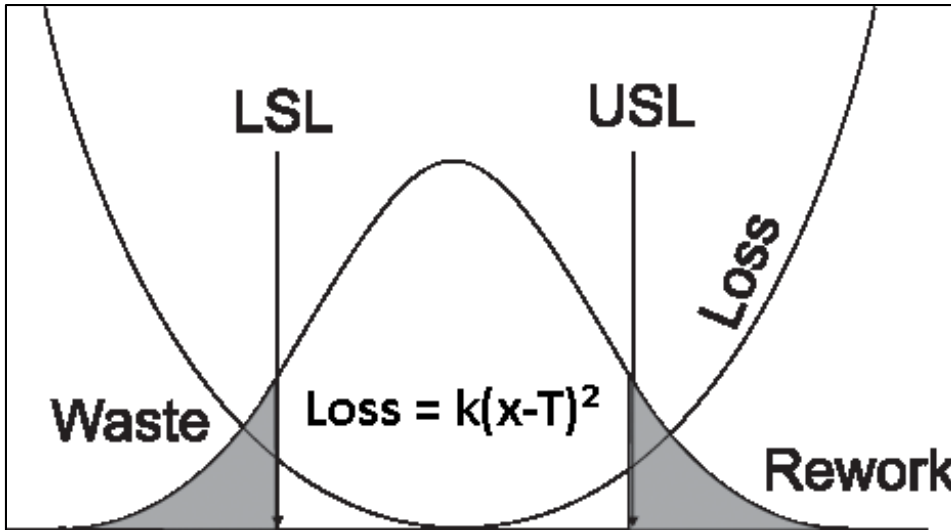


SURVIVABLE

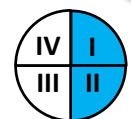
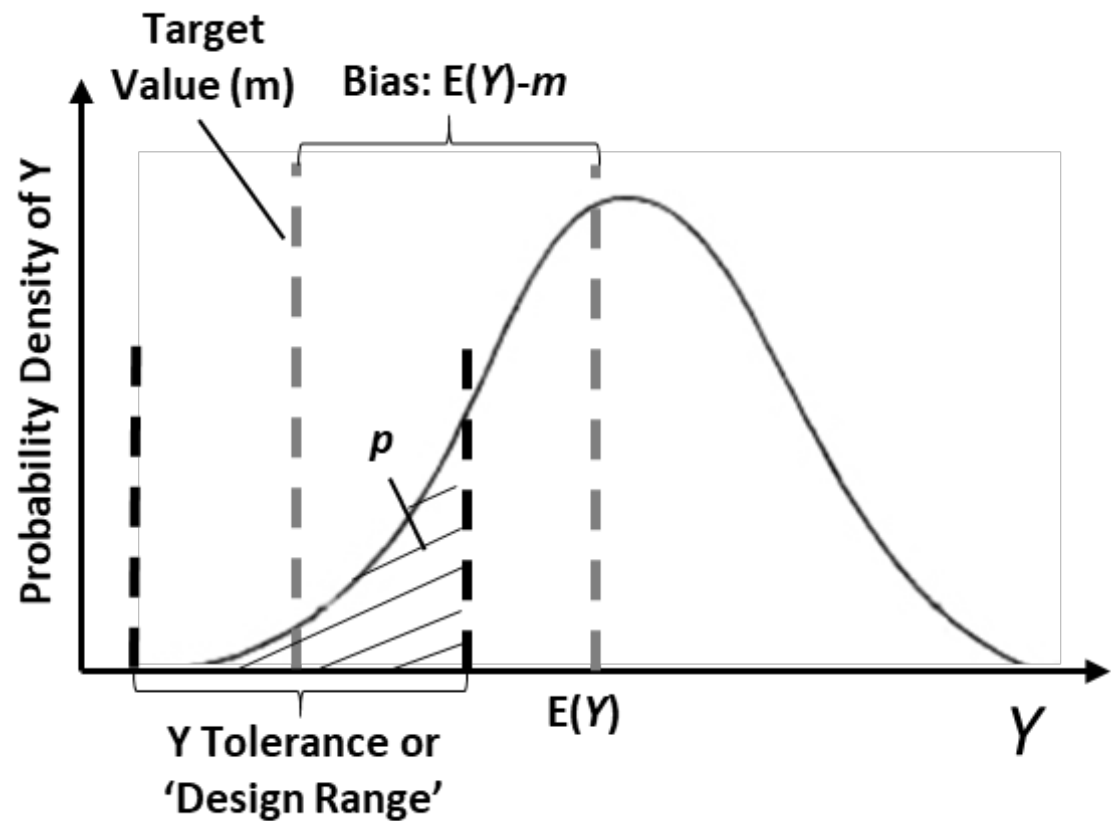
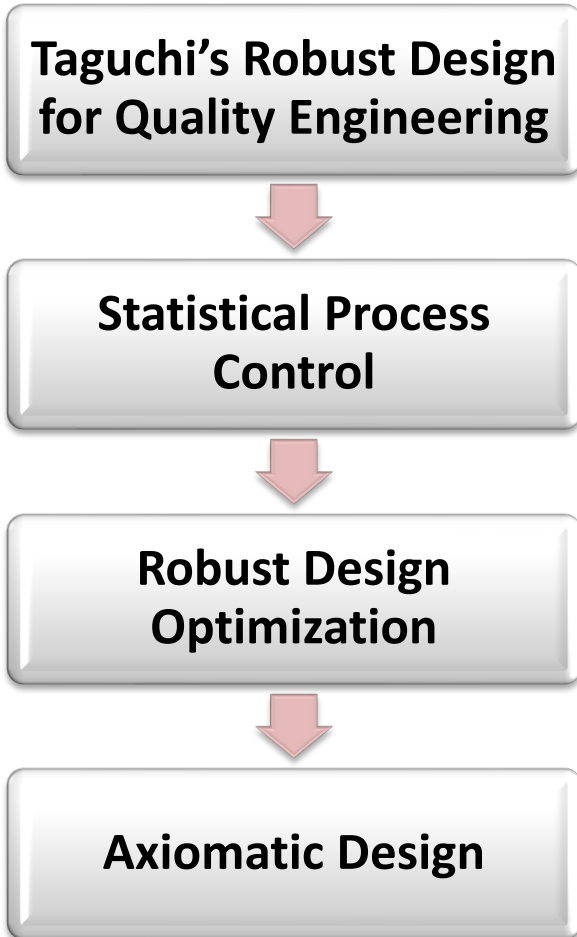
Insensitivity of performance (i.e. maintaining habitability) to

- 1) Random expected failures and conditions (reliability)
- 2) Foreseen but unexpected deviations in conditions or disturbances (resilience)
- 3) Unforeseen disturbances or adverse events (survivability)

ROBUST DESIGN DEFINITIONS AND CONCEPTS



EVOLUTION OF ROBUST DESIGN





ROBUST DESIGN METHODOLOGY FOR ECLSS

General Methodology →

ECLSS Methodology

1. Define **key product characteristic** (KPC):

Need to define **“Habitability”**

2. Identify & characterize **variation sources**:

Need to characterize **ECLSS inputs, operating conditions, component reliability, etc.**

3. Define or **model system** behavior:

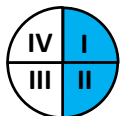
Need mathematical or physical **ECLSS model**

4. **Quantify robustness** of KPC given variation & system model:

Need an **ECLSS robustness metric**

5. Select or **improve design**:

Identify design features **contributing to habitability loss w/ minimum cost of quality**





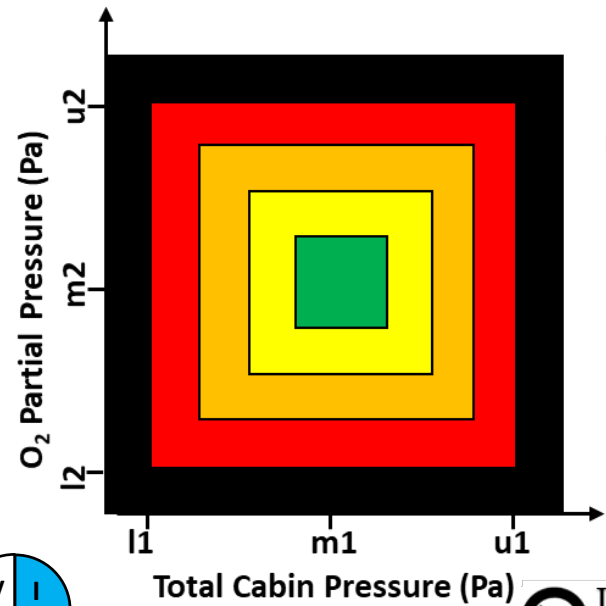
QUANTIFYING ECLSS ROBUSTNESS



HABITABILITY INDEX: ECLSS KPC

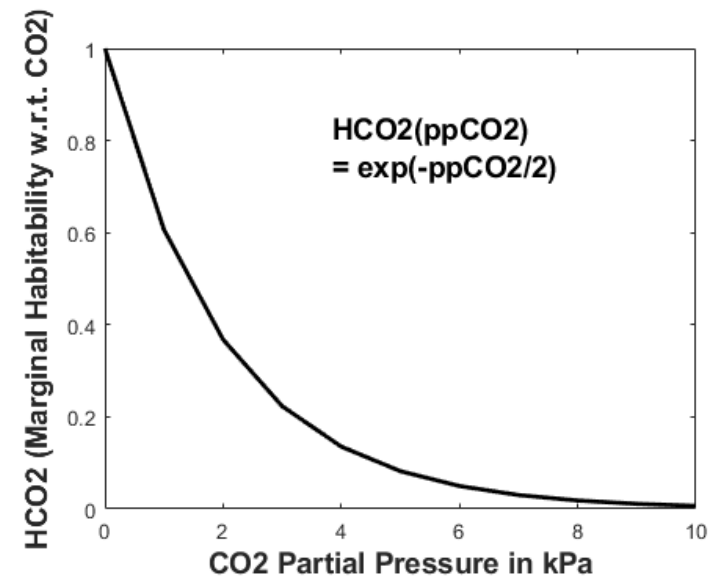
Potential Habitability Contributors (y_i) → Map to Utility Functions, $H_i \in [0,1]$

1. O₂ partial pressure in cabin air
2. CO₂ partial pressure in cabin air
3. Total cabin pressure
4. Wet bulb temperature
5. Food quality (days of available acceptable food per CM)
6. Water quality (days/CM)
7. Presence of noxious substances



Mapping of Environmental Conditions to Marginal Habitability

H=1, No Health Effect
H<0.75, Symptomatic
H<0.5, Ill or Injured
H<0.25, Incapacitated
H=0, Fatal





HABITABILITY INDEX

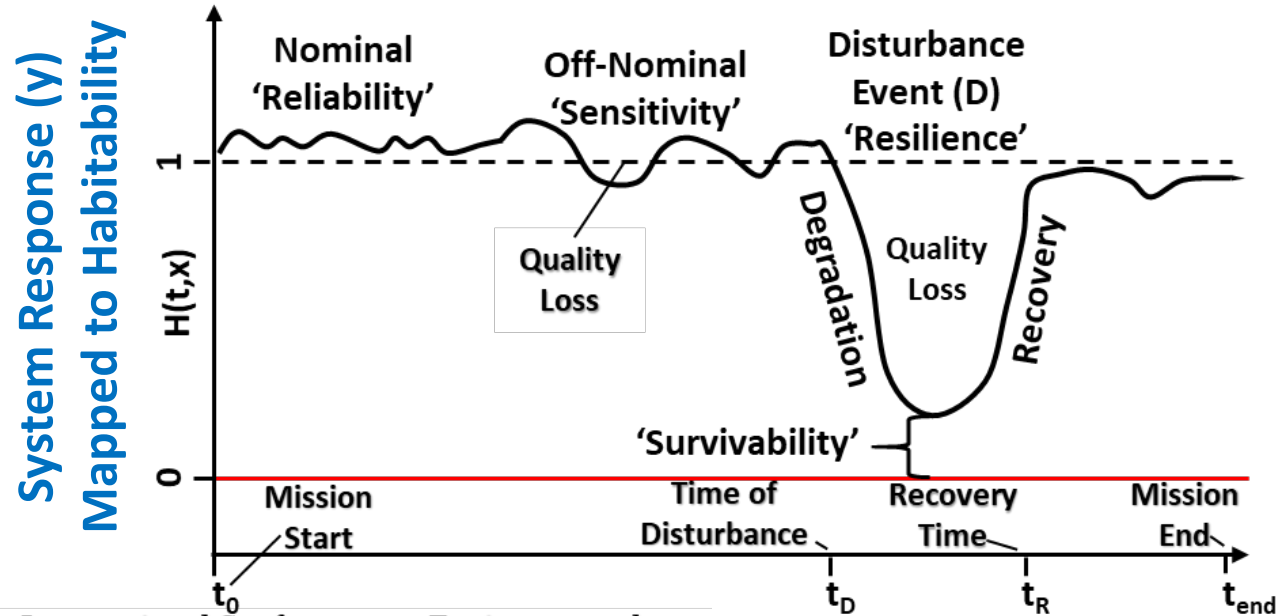


1. H must be 1 when crew performance capacity is full \rightarrow all H_i are equal to 1.
2. H must be 0 under any fatal conditions, i.e. when any $H_i = 0$.
3. H must be no better than any individual H_i , i.e. $H \leq \min(H_i)$
4. The impact of H_i on H is not independent. A reduction in one H_i increases the impact of another H_i .

Habitability Over Mission Duration

$$H = \prod H_i,$$

for $i = 1, \dots, n$
& $H_i \in [0, 1]$

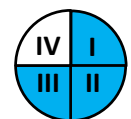


ROBUSTNESS METRICS



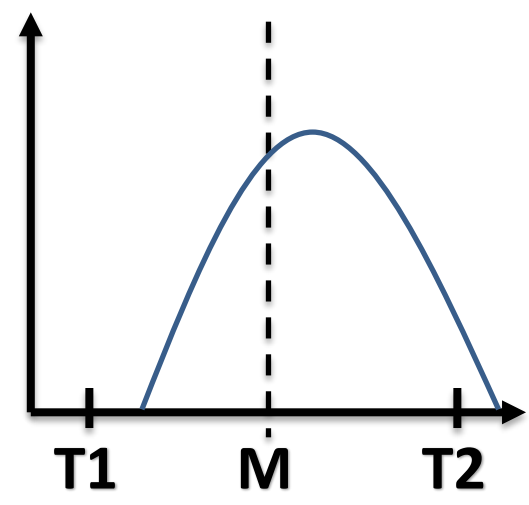
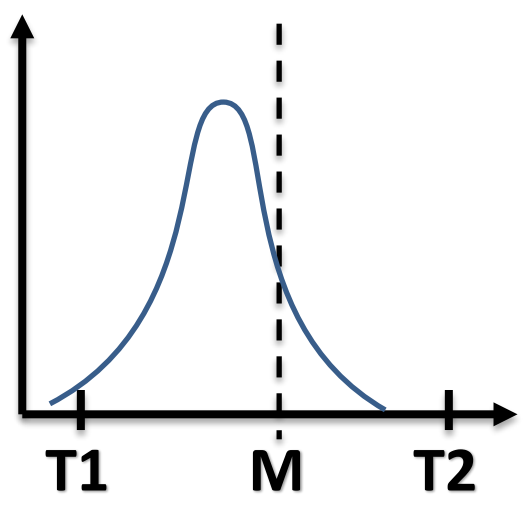
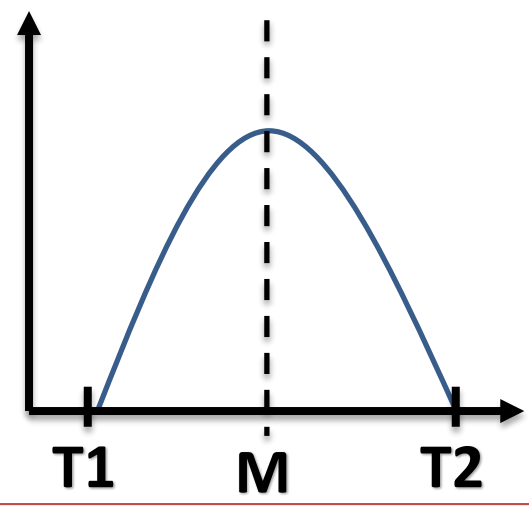
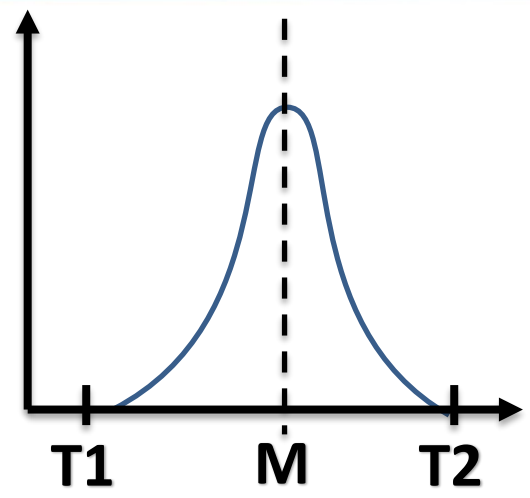
1. **Variance** → $\text{Min Var}(Y|\mathbf{x})$
2. **Effective Fitness** → $\text{Max } E(Y|\mathbf{x})$
3. **Minimax Optimization (Worst Case Philosophy)** →
Choose design parameter that minimizes the worst case value of response Y , given variation in input X
4. **Process Capability Index** → $\text{Max } \Delta/6\sigma$
5. **Quality Loss:** $\text{Min } E(L) = E[k(y-m)^2] = k[(\mu-m)^2 + \sigma^2]$
6. **Sensitivity:** $\text{Min } \delta y/\delta x$ (sensitivity coefficients) a.k.a. Jacobian
7. **Signal to Noise (Taguchi):** $\text{Max } \eta = 10\log_{10}\mu^2/\sigma^2$
8. **Mean + Variance Weighted sum:** $\text{min } (1-\omega)E(y|\mathbf{x}) + \omega\text{Var}(y|\mathbf{x})$
9. **Variation Risk Priority #** → Method to approximate $\text{Var}(Y|\mathbf{x})$ when design fidelity is low
10. **Information Content (Axiomatic Design):** $\text{Min } I = \log_2(1/p)$

See Paper for Details





BIAS VS SPREAD: WHICH IS WORSE?





\mathcal{R}_H - A PROPOSED METRIC FOR ECLSS ROBUSTNESS



➤ **Habitability Loss:**

$$L_H = (H-1)^2$$

➤ **Expected Habitability Loss:**

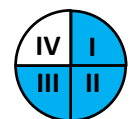
$$E[L_H] = E[(H-1)^2] = [1-E(H)]^2 + \text{Var}(H)$$

➤ **ECLSS Robustness:**

$$\mathcal{R}_H = 1 - \sqrt{E(L_H)} = 1 - \sqrt{[(1 - E(H))^2 + \text{Var}(H)]}$$

'bias'

'spread'





IMPROVING ECLSS ROBUSTNESS





ROBUST DESIGN METHODOLOGY FOR ECLSS

General Methodology



ECLSS Methodology

1. Define **key product characteristic** (KPC):



Need to define **“Habitability”**

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Need to characterize **ECLSS inputs, operating conditions, component reliability, etc.**

3. Define or **model system** behavior:



Need mathematical or physical **ECLSS model**

4. **Quantify robustness** of KPC given variation & system model:



Need an **ECLSS robustness metric**

5. Select or **improve design**:

Identify design features **contributing to habitability loss w/ minimum cost of quality**



IMPROVING ROBUSTNESS: DEFENSE IN DEPTH STRATEGY

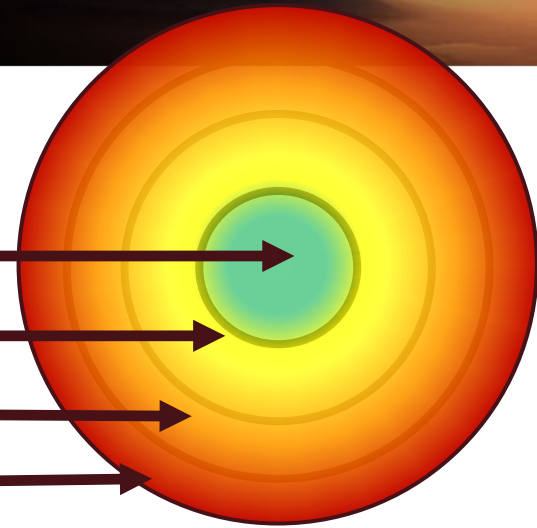


Many Design Options to Consider:

- Materials, technology choices
- Margin
- Tolerancing
- Redundancy (many types)
- Fault detection & isolation
- Repair/recovery
- Noise reduction through shielding, etc.
- Process changes
- Decrease complexity
- Decrease coupling (controllability)

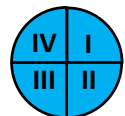
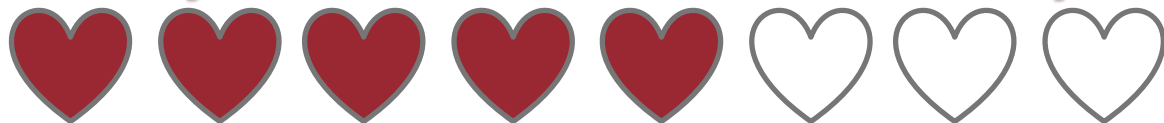
Design for:

- Quality
- Reliability
- Resilience
- Survivability



Good day → Not so good day → Bad Day
Probable → Possible → Plausible
Fail Safe → → → Safe to Fail

Objective: maintain habitability





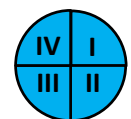
IMPROVING ROBUSTNESS: MINIMIZE COST OF QUALITY

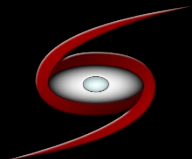


Robustness Normalized ESM (?)

Equivalent mass required to achieve
equivalent robustness

$$ESM_R = ESM / R_H$$





NEXT STEPS



- **Development of Marginal Habitability Functions for ECLSS sub-systems**

Requires cooperative research amongst subject matter experts!

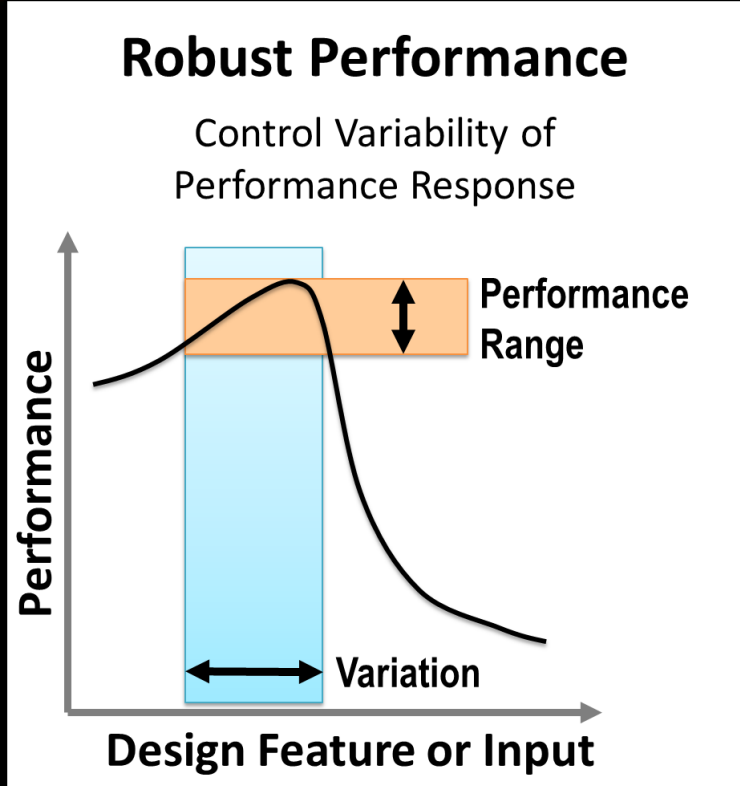
- **Demonstrate ECLSS robustness analysis with historical data (ISS, etc.)**
- **Demonstrate robust design methodology**

Reaching consensus on marginal utility functions contributing to habitability will be challenging, but instrumental in improving ECLSS design



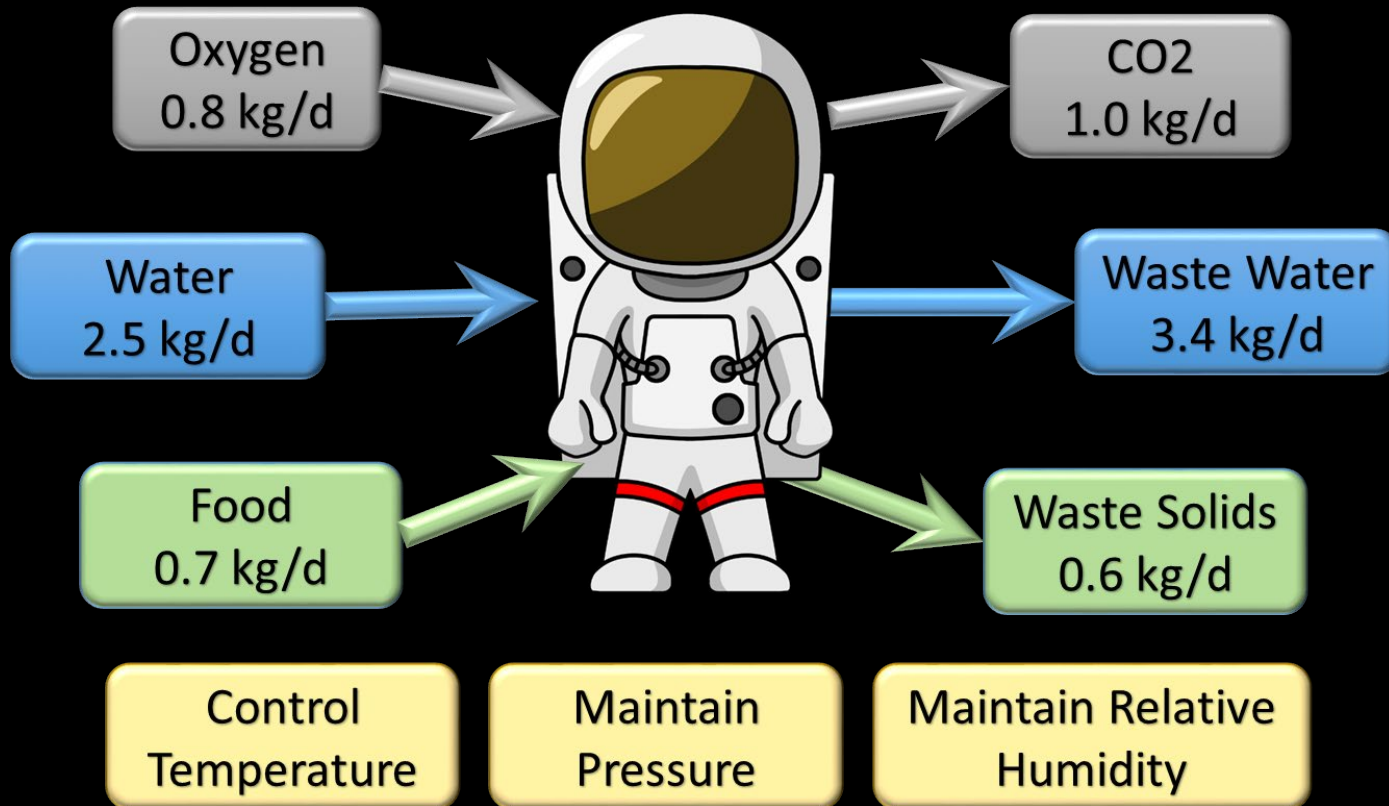


QUESTIONS?



ECLSS DESIGN DRIVERS

Human Metabolic Inputs & Outputs

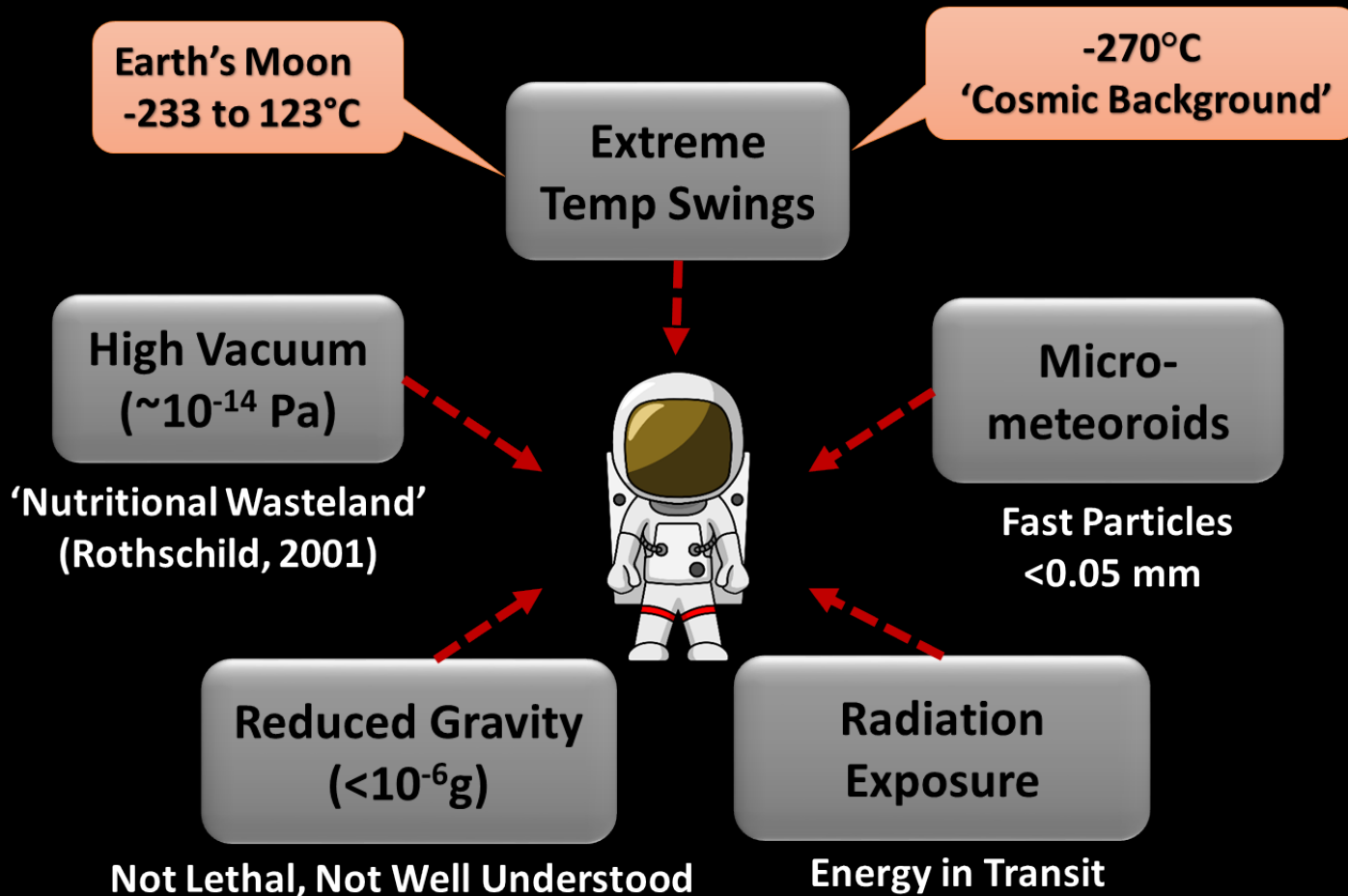


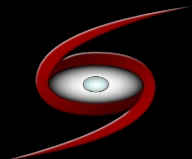
BVAD 2015 (pp 50, 53, 64, & 106)



ECLSS DESIGN DRIVERS

Interplanetary Environment





ECLSS DESIGN DRIVERS

Mission Characteristics

- Mass & Volume Constraints
- EVA Activity
- Crew Workload
- Surface Operations
- Distance from Earth



NASA Exploration Systems Architecture Study

https://www.nasa.gov/pdf/140649main_ESAS_full.pdf

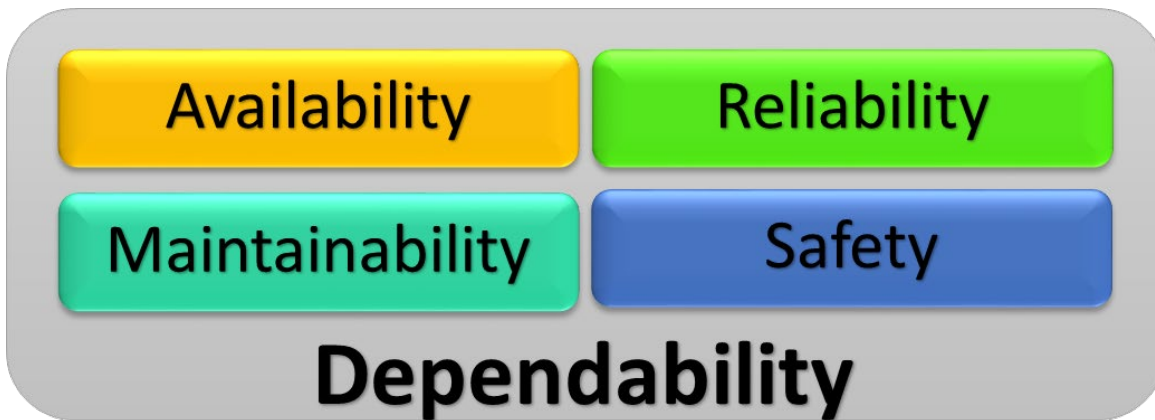




Reliability Definition

“The probability of a system or system element performing its intended function under stated conditions without failure for a given period of time.”

Adcock, 2016





Resilience Definition



**“The capacity to recover quickly from difficulties;
toughness”**

**“The ability of a substance or object to spring back into
shape; elasticity”**

Oxford Dictionary

Engineering definitions vary widely:

- Ability to adapt to changing conditions and prepare for, withstand, and rapidly recover from disruption (DHS)
- Attributes include flexibility, recovery, and adaptation





Defining Survivability



Ability of a system to **minimize the impact of a finite disturbance on value delivery**, achieved through either the satisfaction of a minimally acceptable level of value delivery during and after a finite disturbance or the reduction of the likelihood or magnitude of a disturbance

Castet et al., 2008

